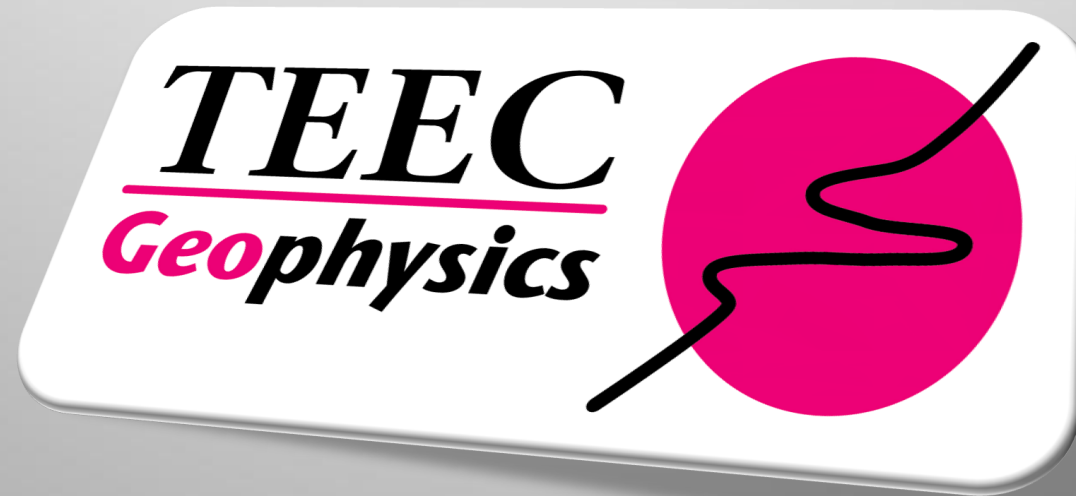


Common Reflection Surface theory and worldwide data examples

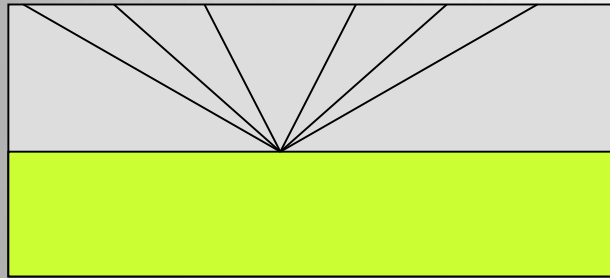


Common Reflection Surface (CRS) processing

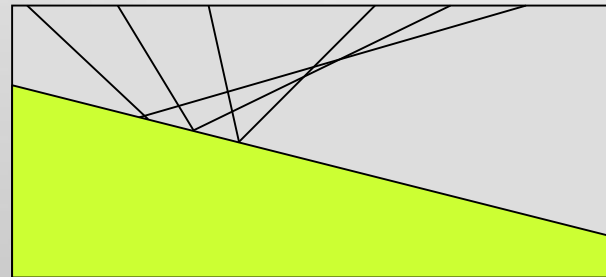
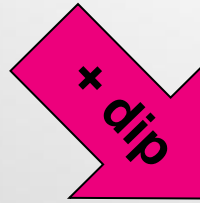
Data driven approach

- **stacking parameters are determined from data**
- **local parameter search at each point of stack**
- **selection of parameter by coherency measures along stacking surfaces**

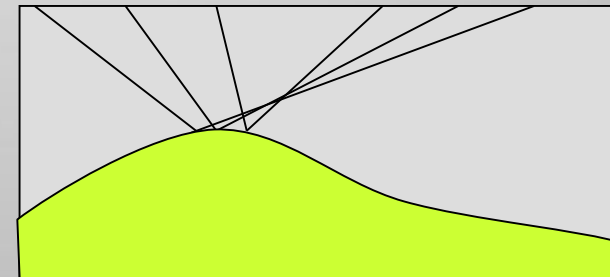
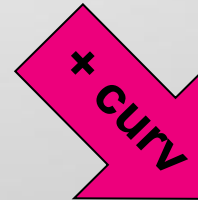
CRS Basics – Generalization of the subsurface model



CMP Processing
(Mayne, 1962)

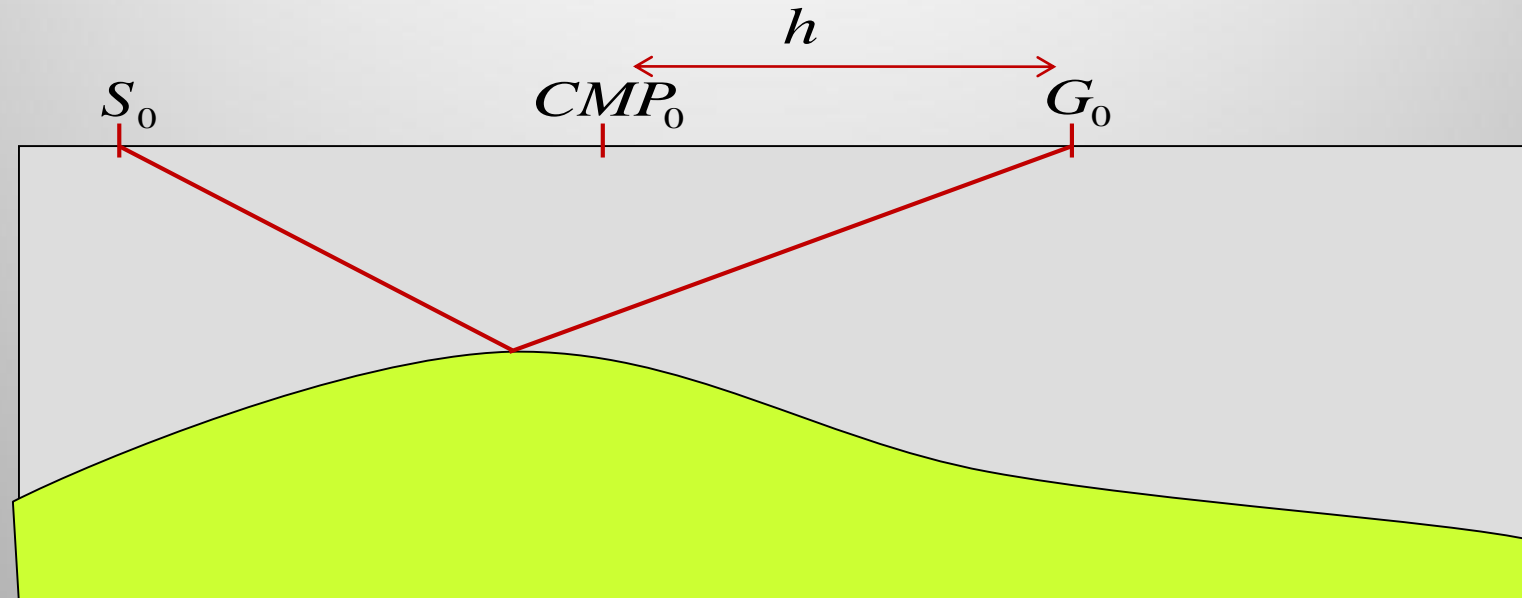


DMO Processing
(Hale, 1991)



CRS Processing
(Hubral, 1999)

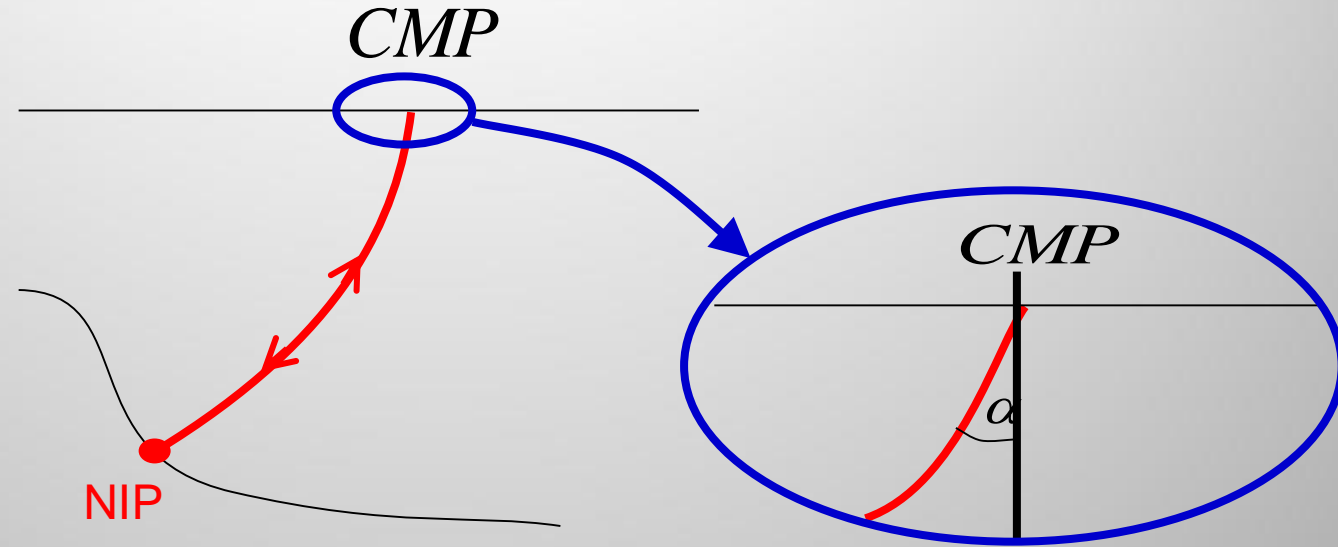
CRS Basics – Generalization of the subsurface model



$$t^2(h) = t_0^2 + \frac{4h^2}{v_{NMO}^2}$$

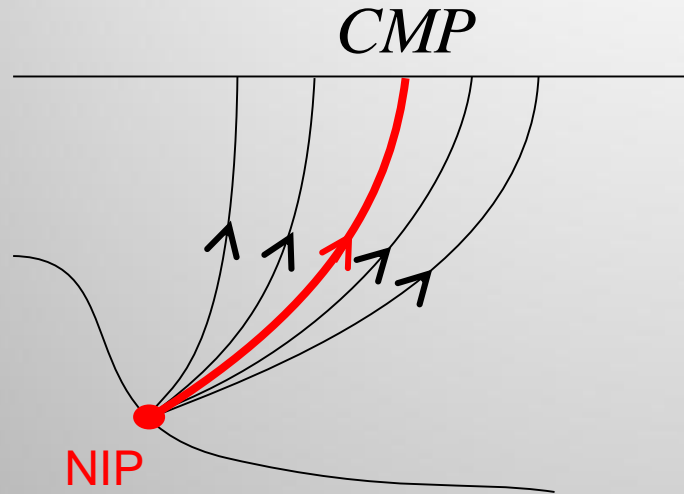
1 Parameter : V_{NMO}

CRS Basics – Generalization of the subsurface model

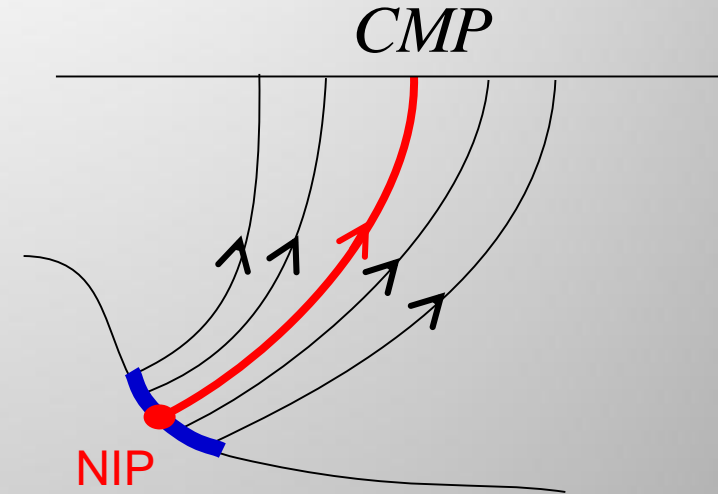


NIP = normal incident point

CRS Basics – Generalization of the subsurface model

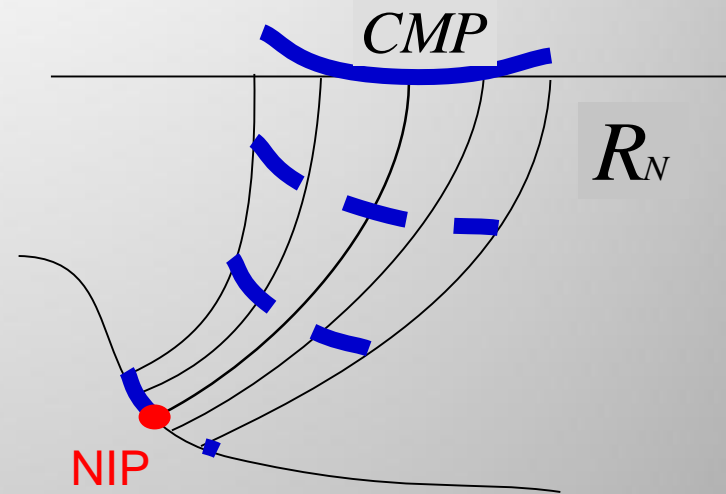
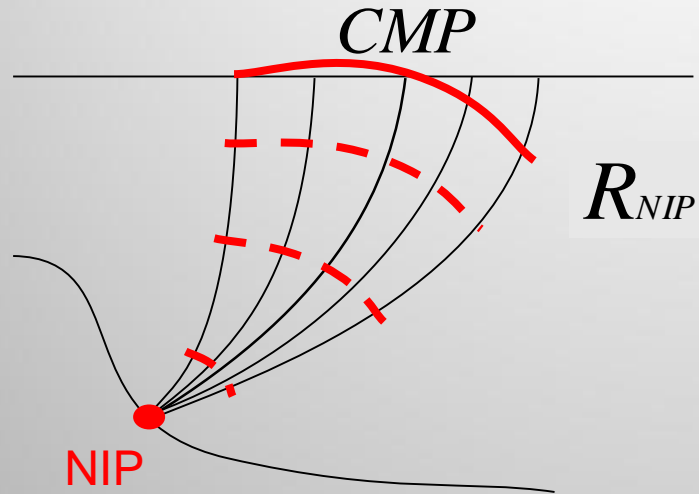


NIP Wave



Normal Wave (or N Wave)

CRS Basics – Generalization of the subsurface model



CRS Basics – Generalization of the subsurface model

NMO versus CRS

NMO Traveltime

$$t^2(h) = t_0^2 + \frac{4h^2}{v_{NMO}^2}$$

1 Parameter : V_{NMO}

NMO Model



CRS Model



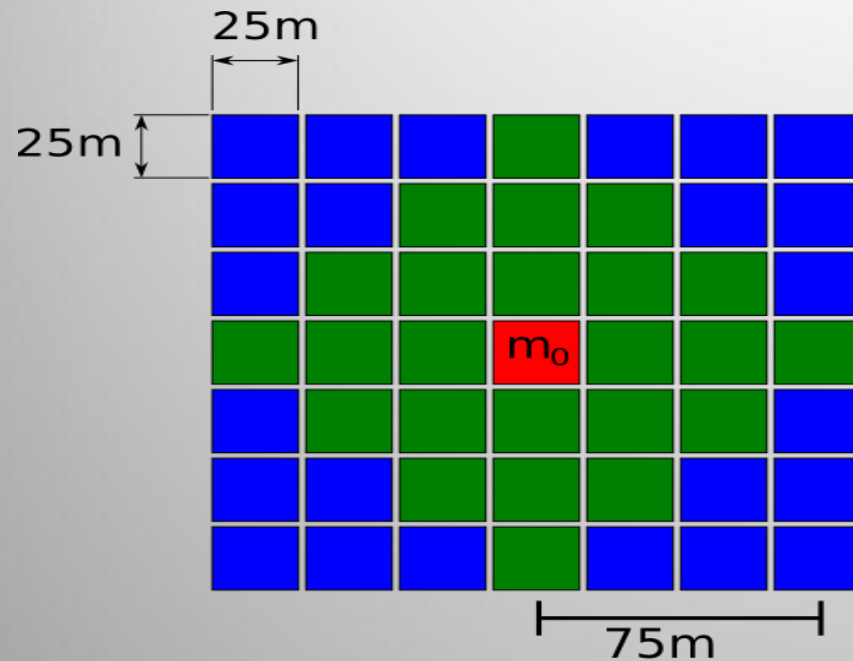
CRS Traveltime

$$t^2 = \left(t_0 + \frac{2 \sin \alpha}{v_0} \Delta x \right)^2 + \frac{2 t_0 \cos^2 \alpha}{v_0} \left(\frac{\Delta x^2}{R_N} + \frac{h^2}{R_{NIP}} \right)$$

3 Parameters: α, R_{NIP}, R_N

CRS Basics – Generalization of the subsurface model

CRS midpoint aperture

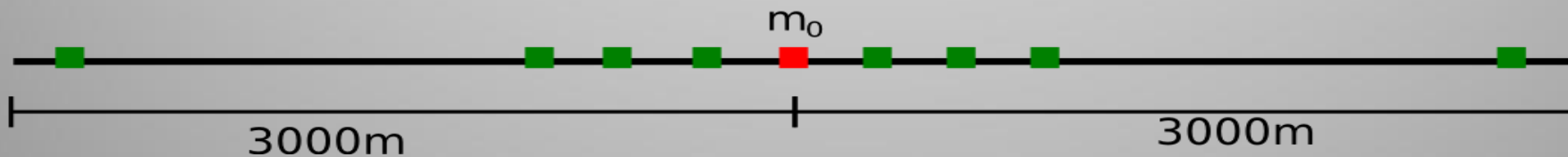


Acquisition info

Cell size: 25m x 25m

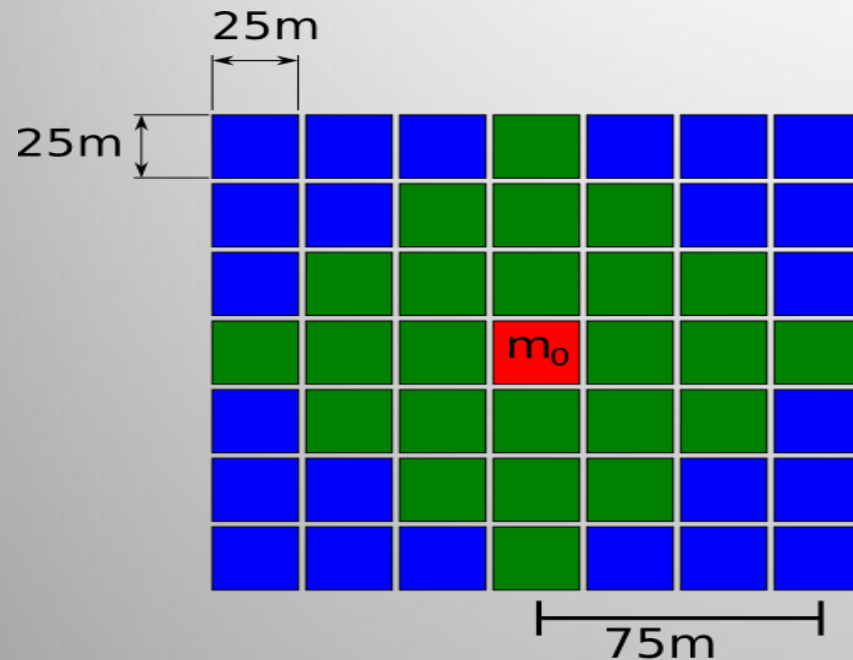
ICMP: 25m

CMP fold: 60 traces



CRS Basics – Generalization of the subsurface model

CRS midpoint aperture



Acquisition info

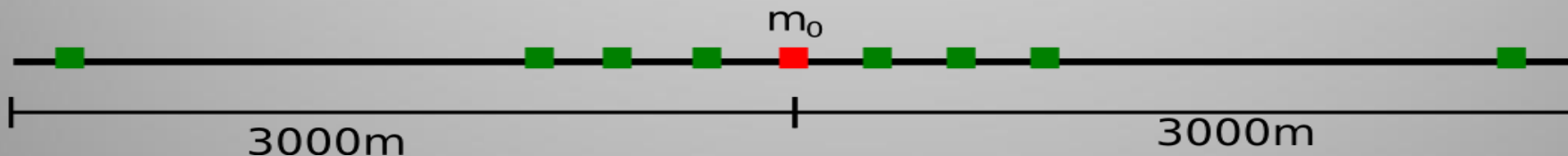
Cell size: 25m x 25m

ICMP: 25m

CMP fold: 60 traces

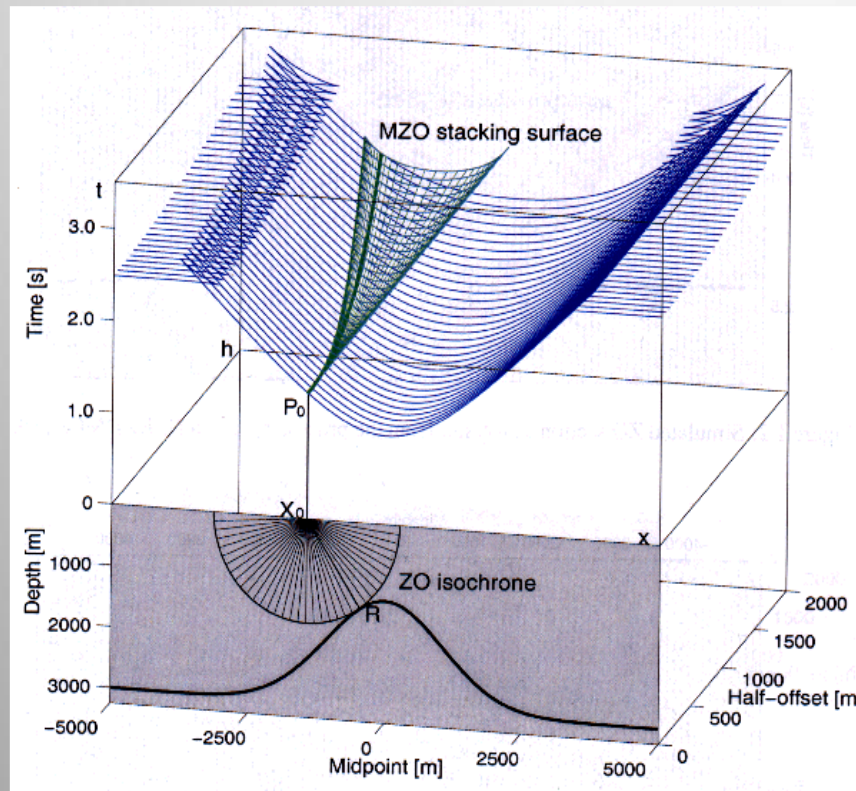
2D: $7 \times 60 = 420$ traces

3D: $7 \times 7 \times 60 = 2940$ traces

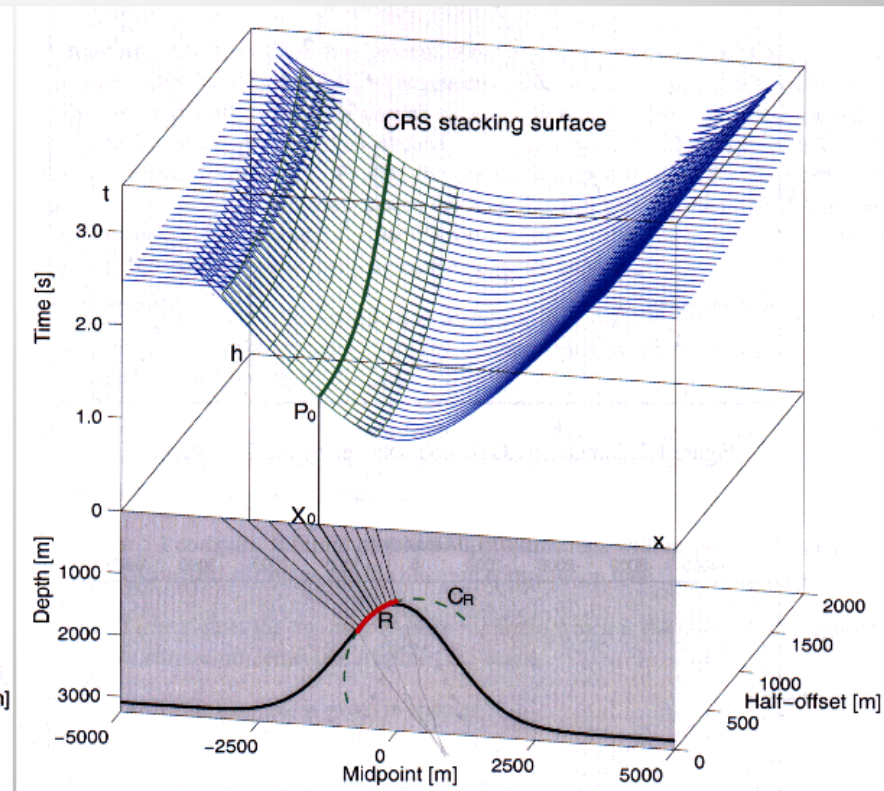


CRS Basics – Generalization of the subsurface model

Fit of stacking surfaces / reflection time surfaces



NMO/DMO



CRS

(Hubral et al. 1999)

CRS Basics – Generalization of the subsurface model

Expected advantages of CRS stacking

- Improved signal-to-noise ratio
- Improved imaging of dipping reflections
- Improved imaging in low fold zones
- More detailed velocity model information

CRS in Complex Tectonic Settings

Alps/Germany

Andes Foreland/Bolivia

Carpathian Mountains/ Poland

Caucasus Mountains/ Russia

Kurdistan/ Irak

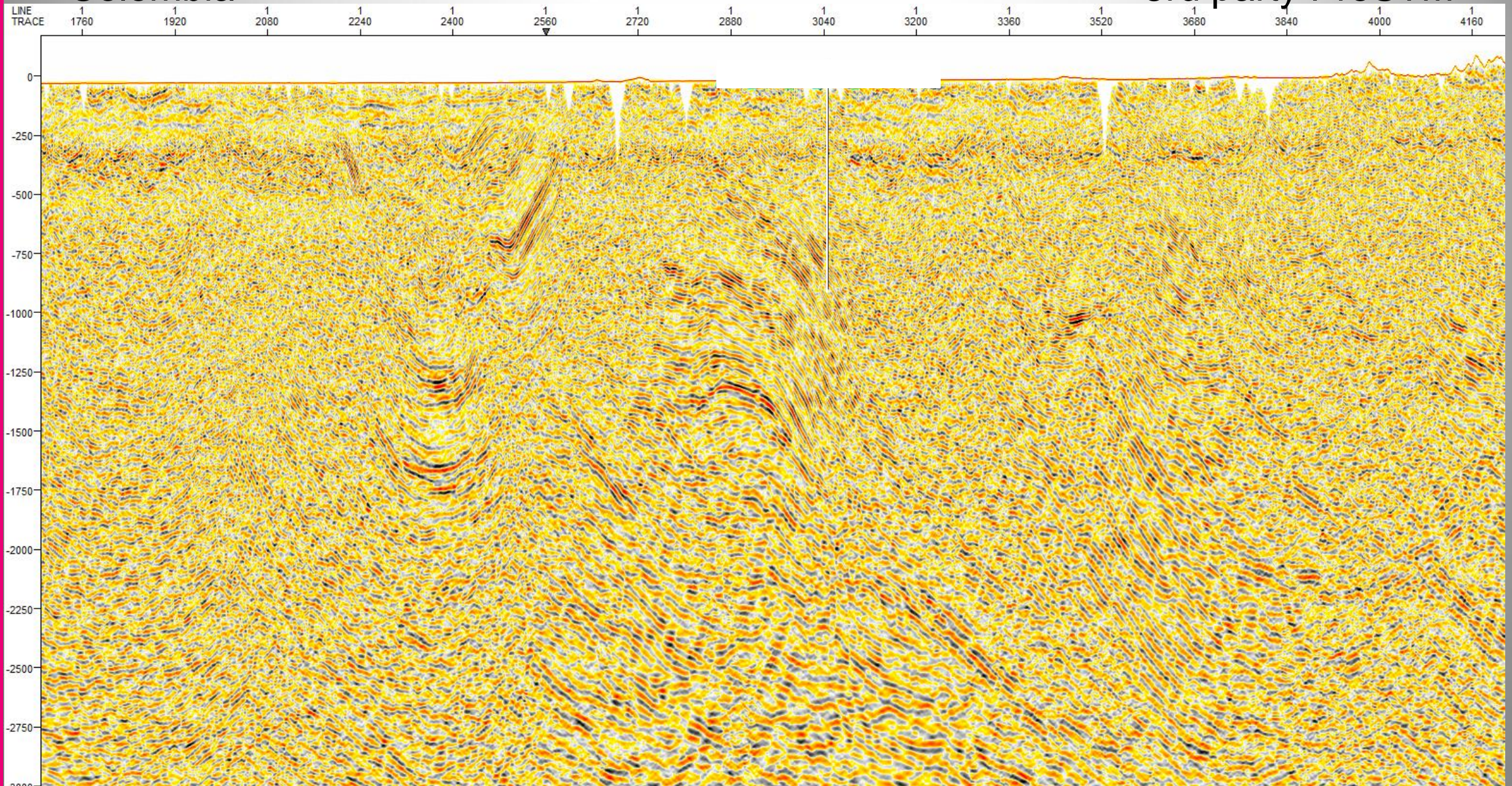
Himalaya Foreland/ India

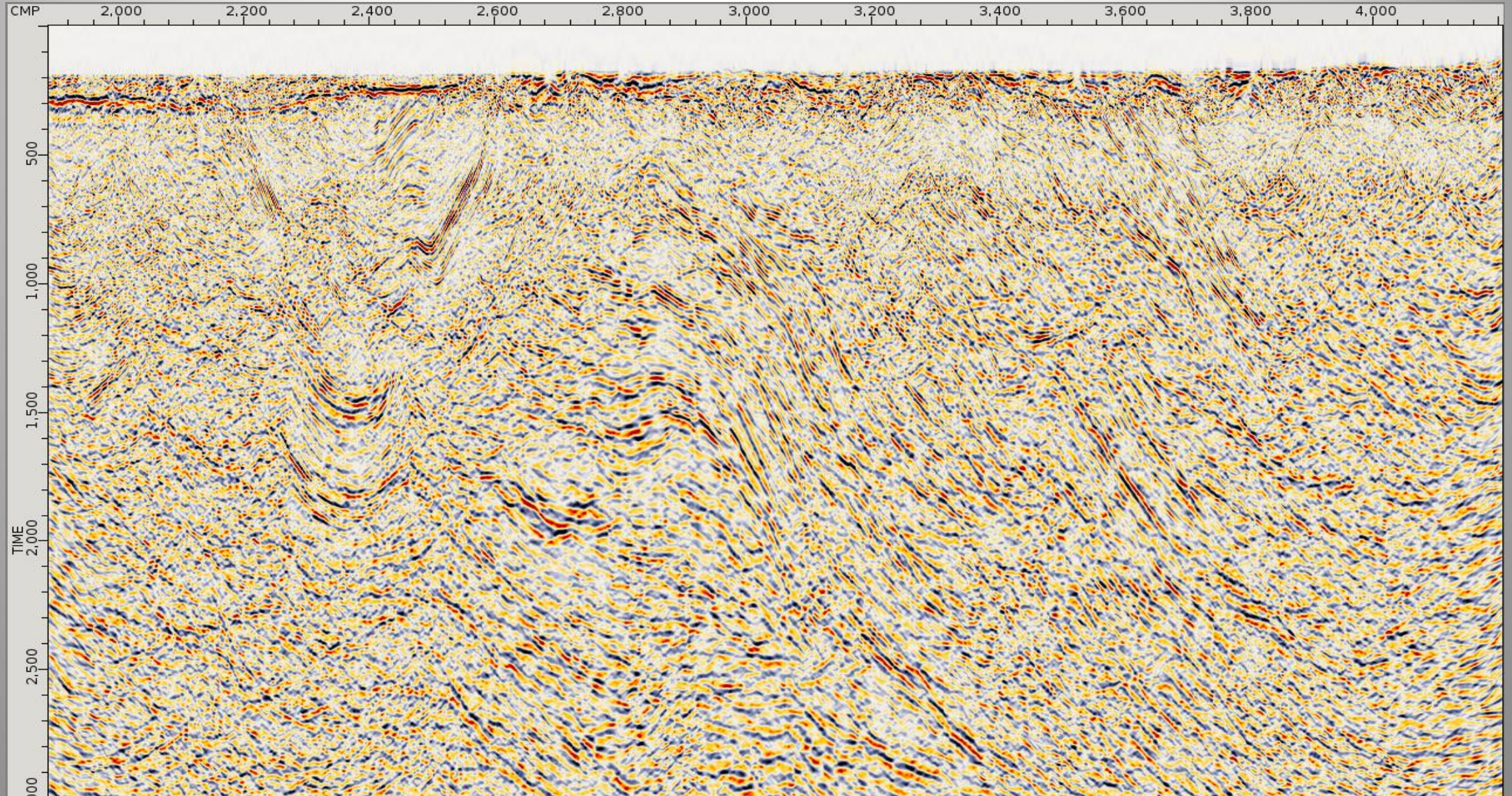
Pyrenees/ Spain

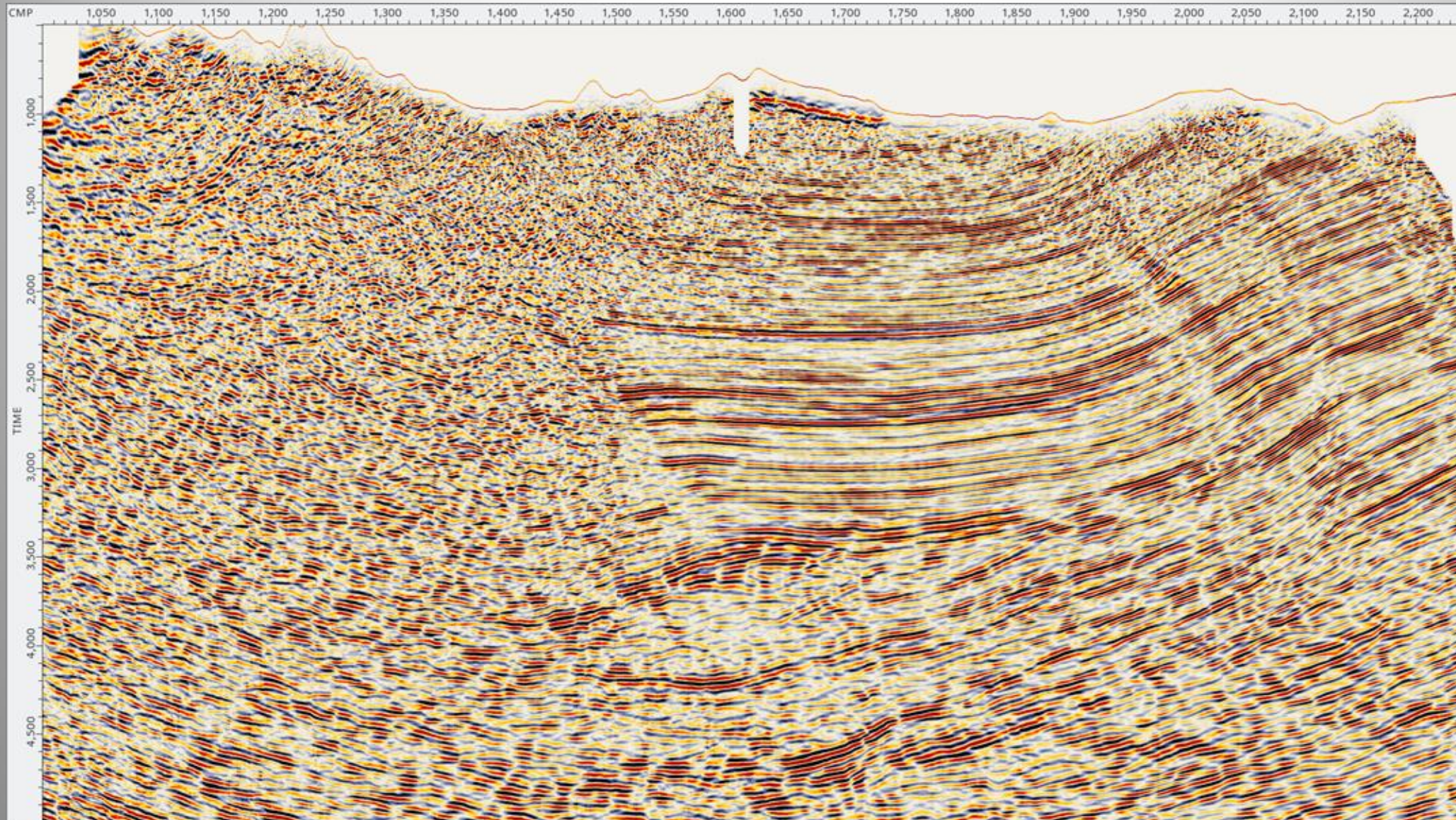
Rockies/ USA

Zagros Mountains/ Iran



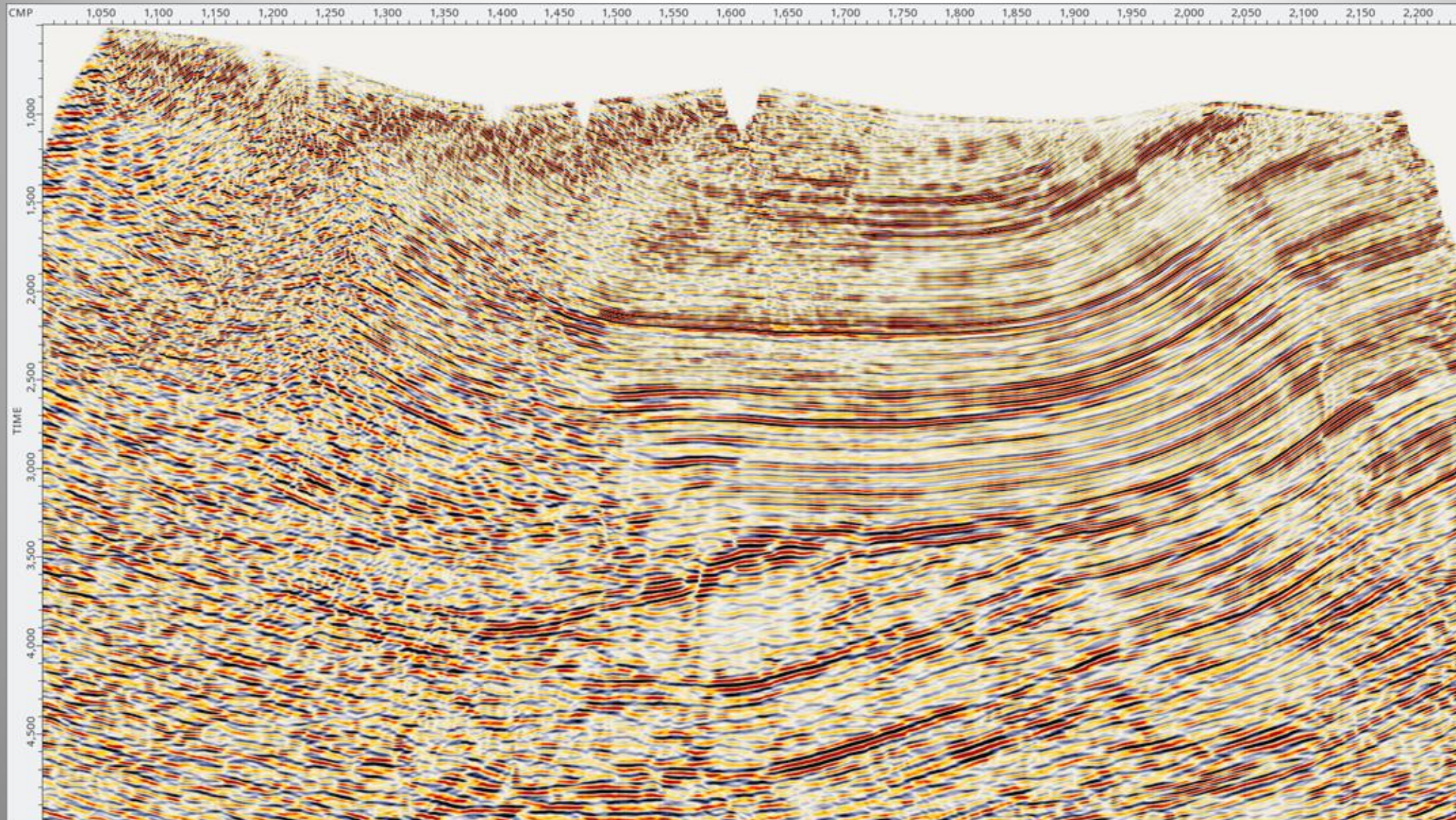




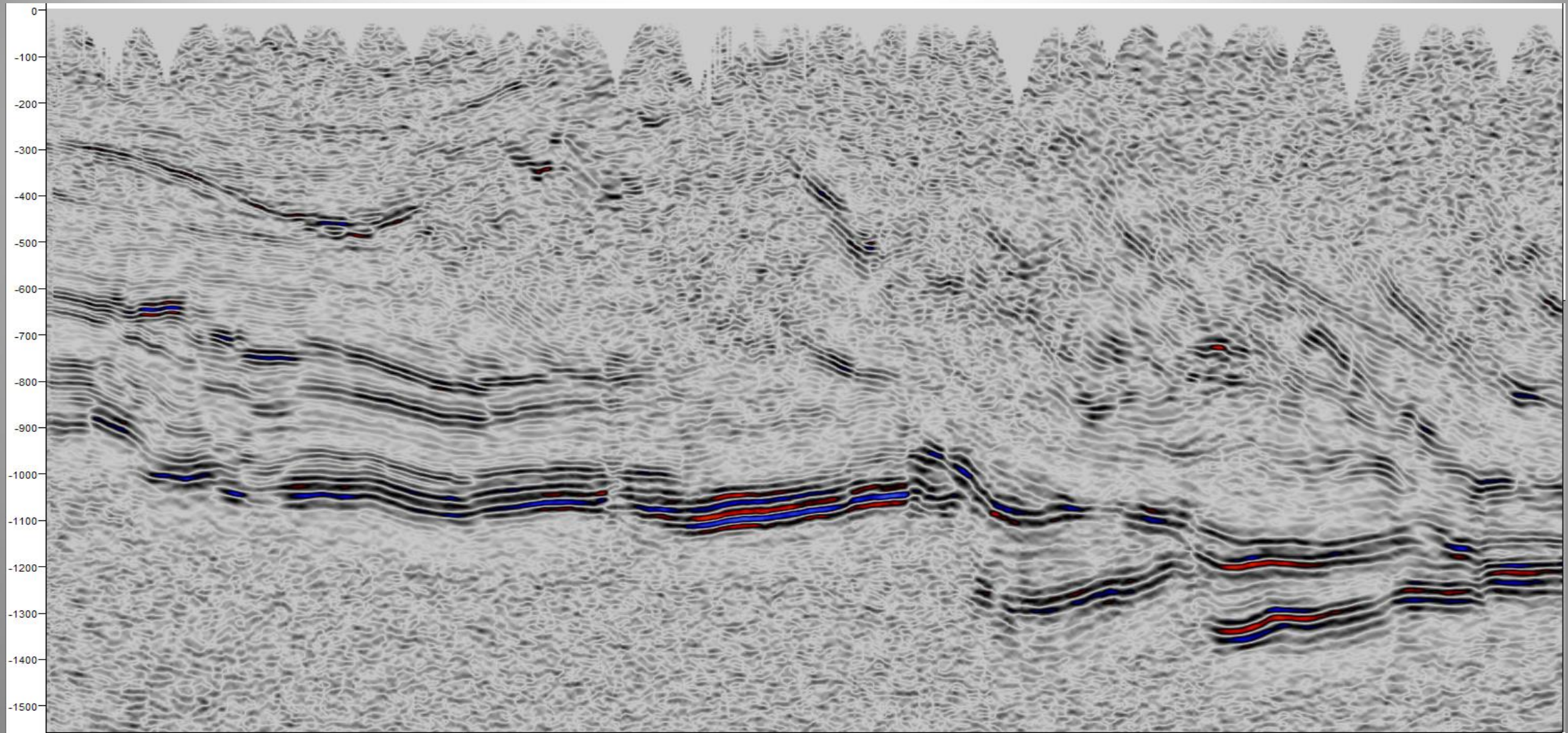


Colombia 2D

TEEC CRS PreSTM

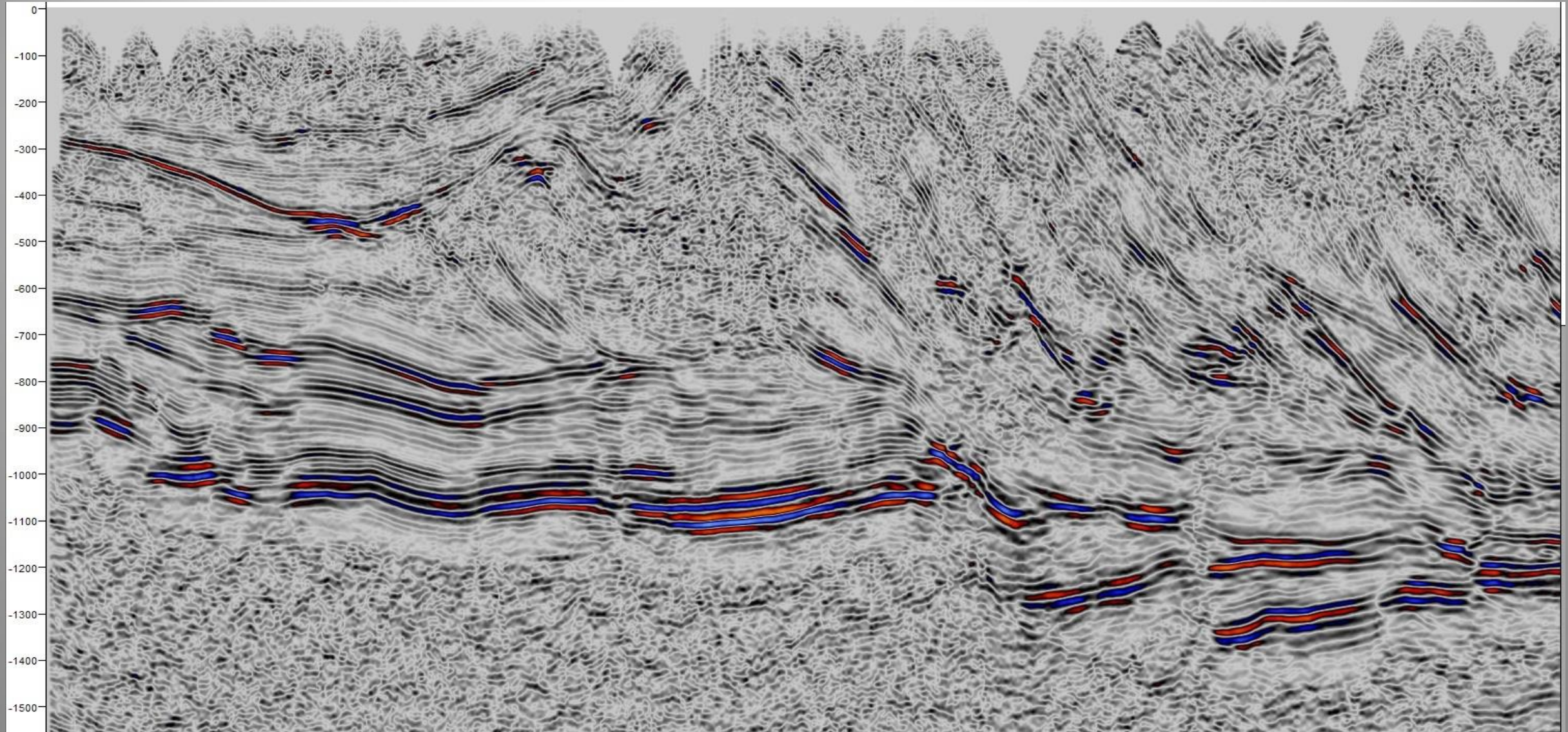


Northern Calcareous Alps



Client Time Migration with conventional processing

Northern Calcareous Alps



TEEC Time Migration with CRS processing

CRS on marine data

North Sea

Gulf of Mexico

Persian Gulf

South China Sea

Carribean Sea

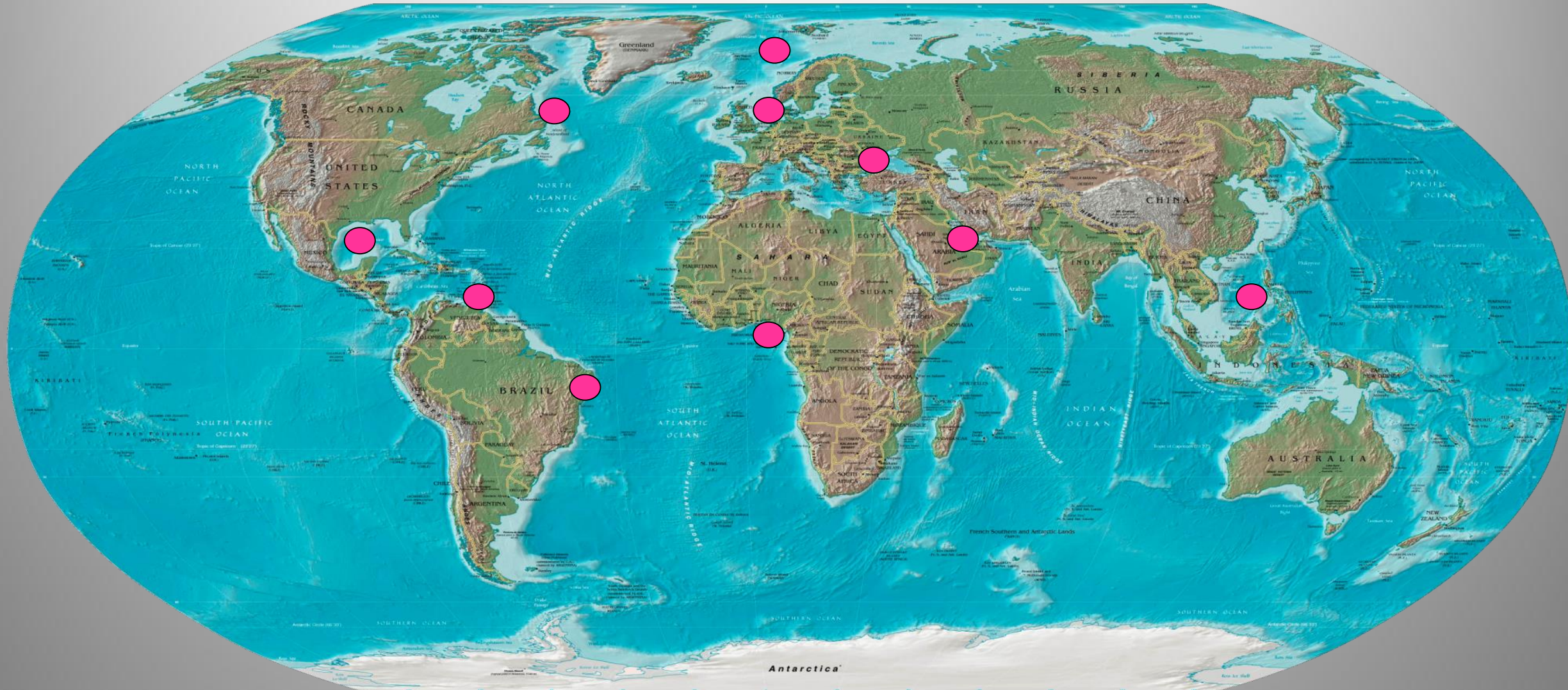
Barent Sea

Black Sea

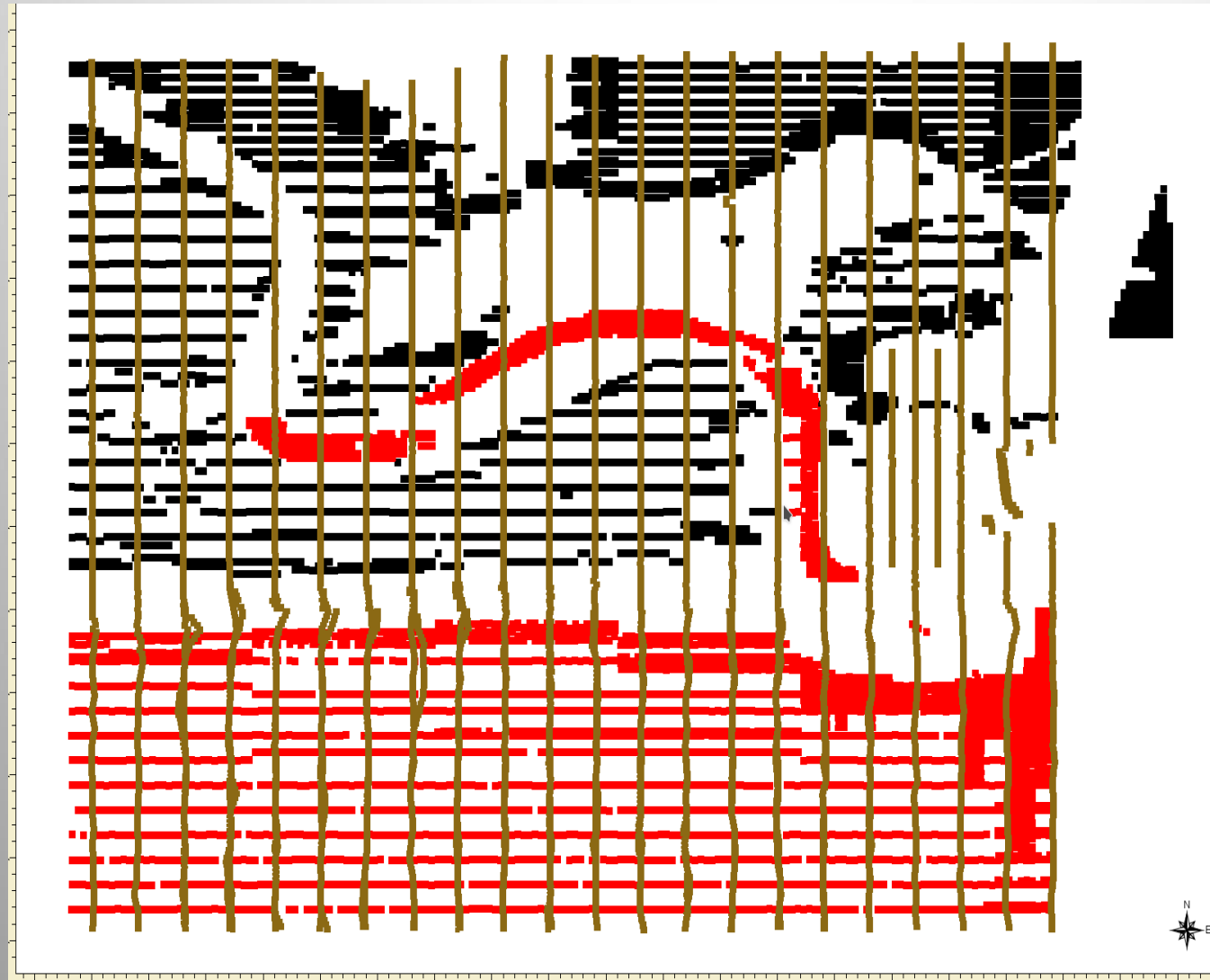
Offshore West Africa

Offshore Nova Scotia

Brasil

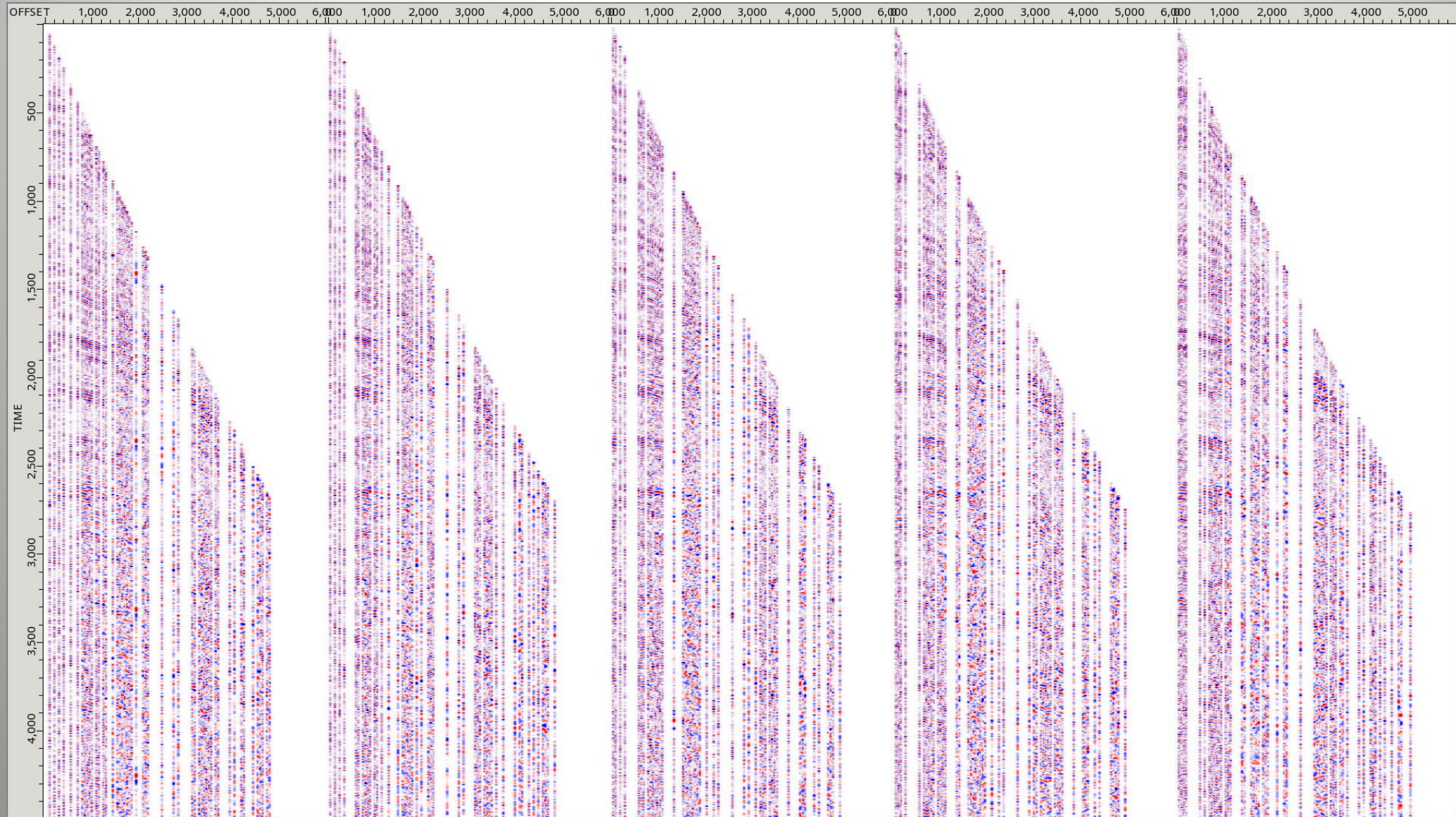


Land/TZ/offshore

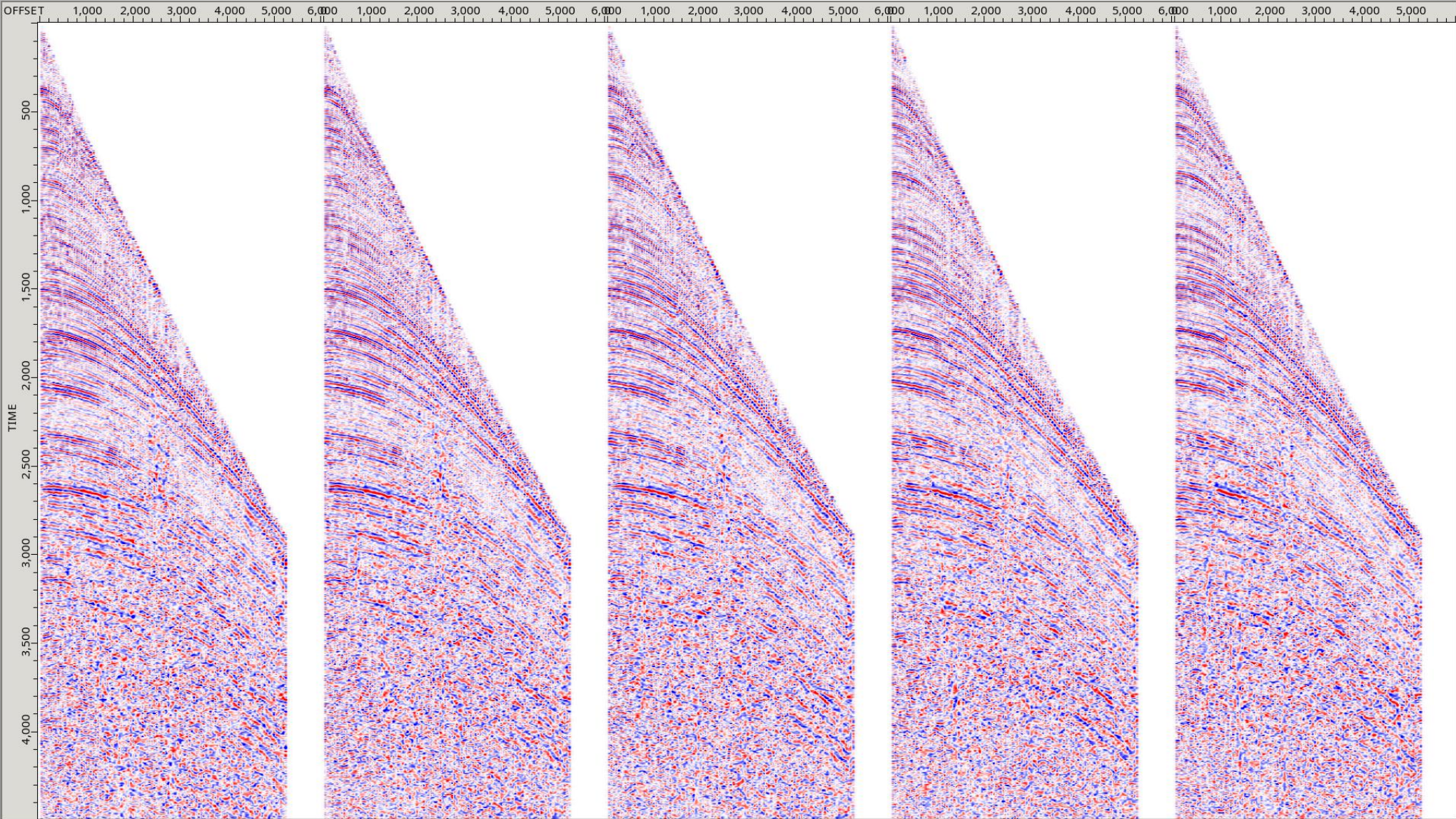


- Sources:
- Explosives in black
- Airguns in red
- Receiver:
- Receiver in brown

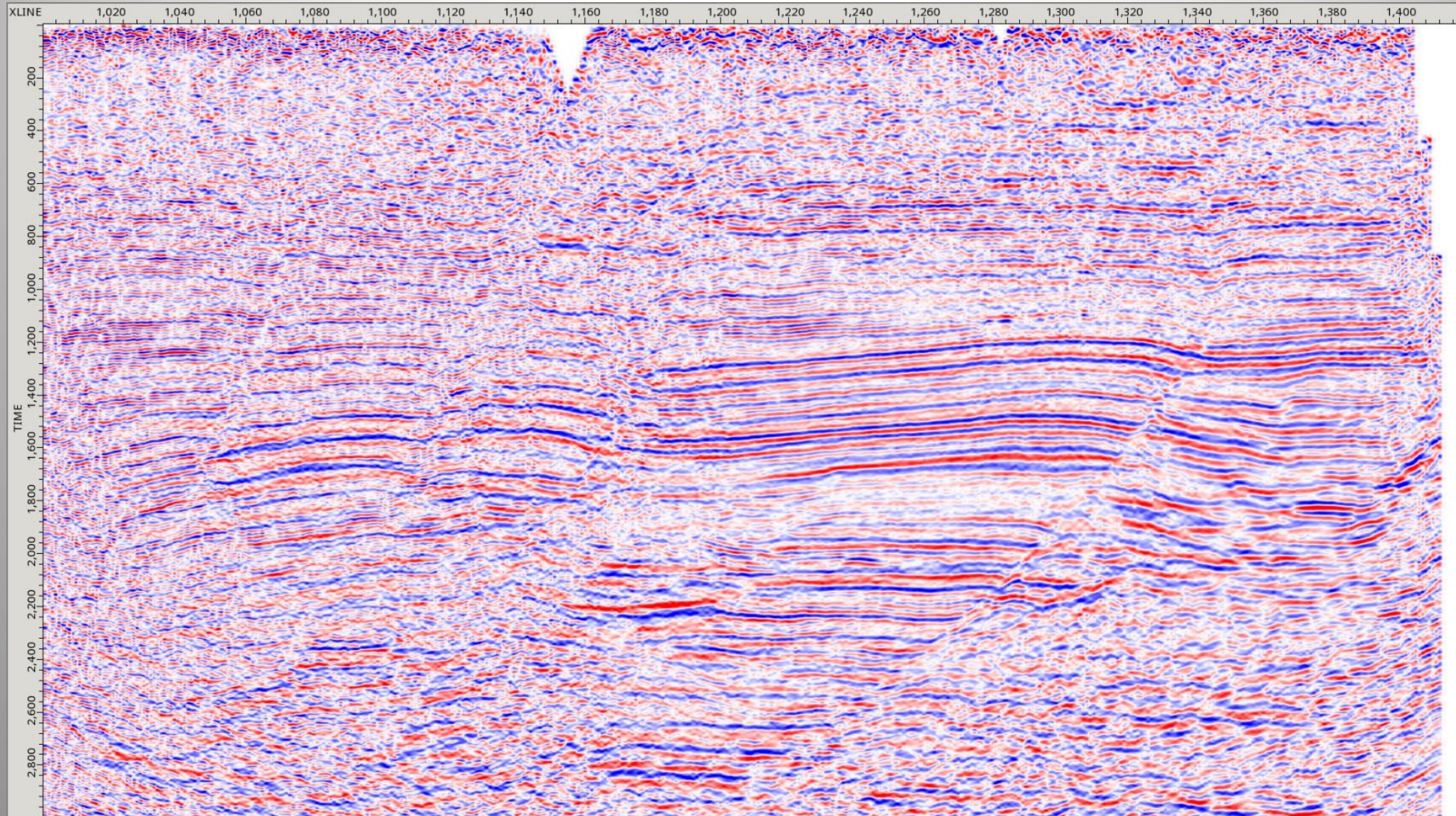
CMP gathers before CRS processing



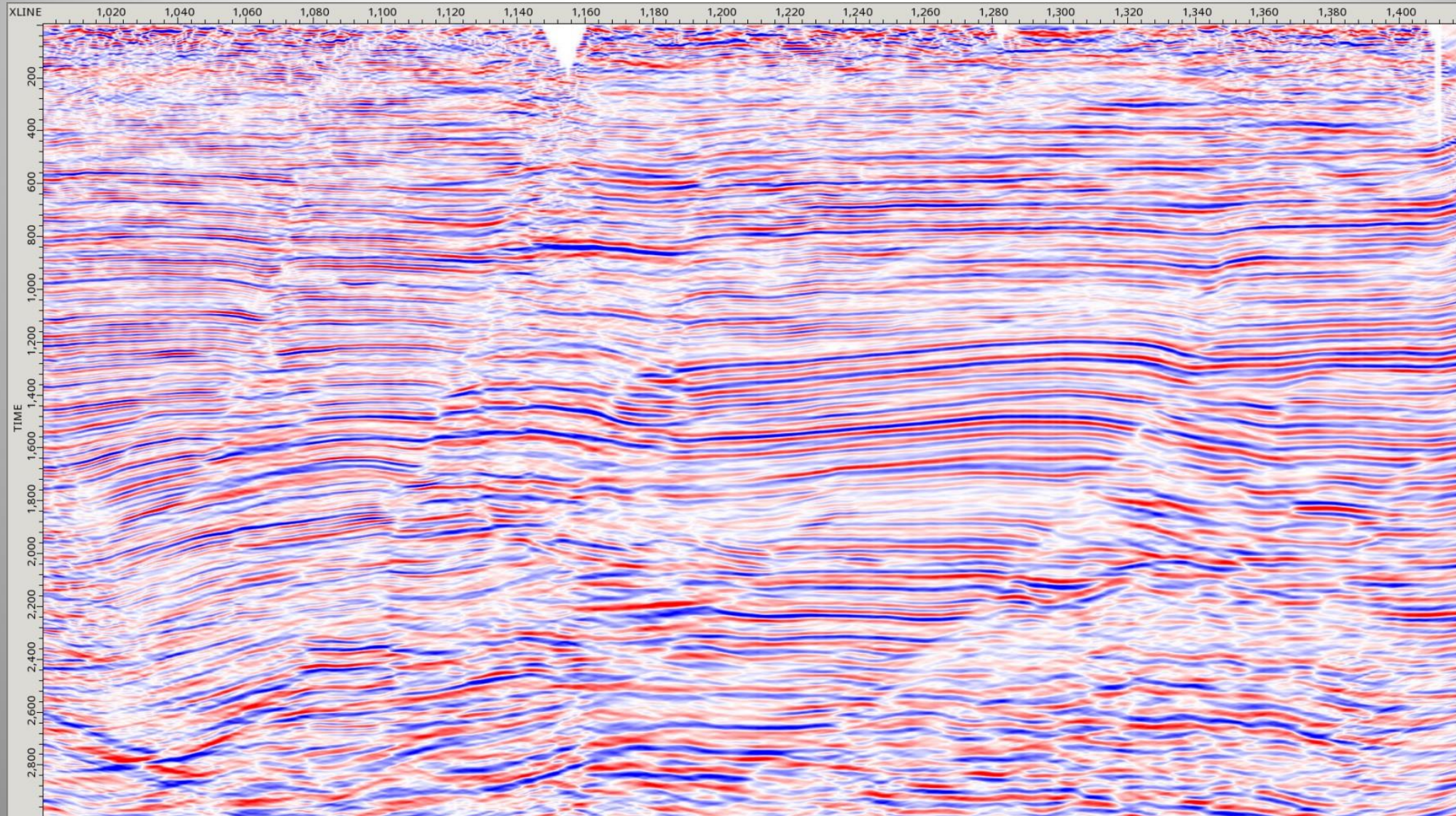
CRS gathers



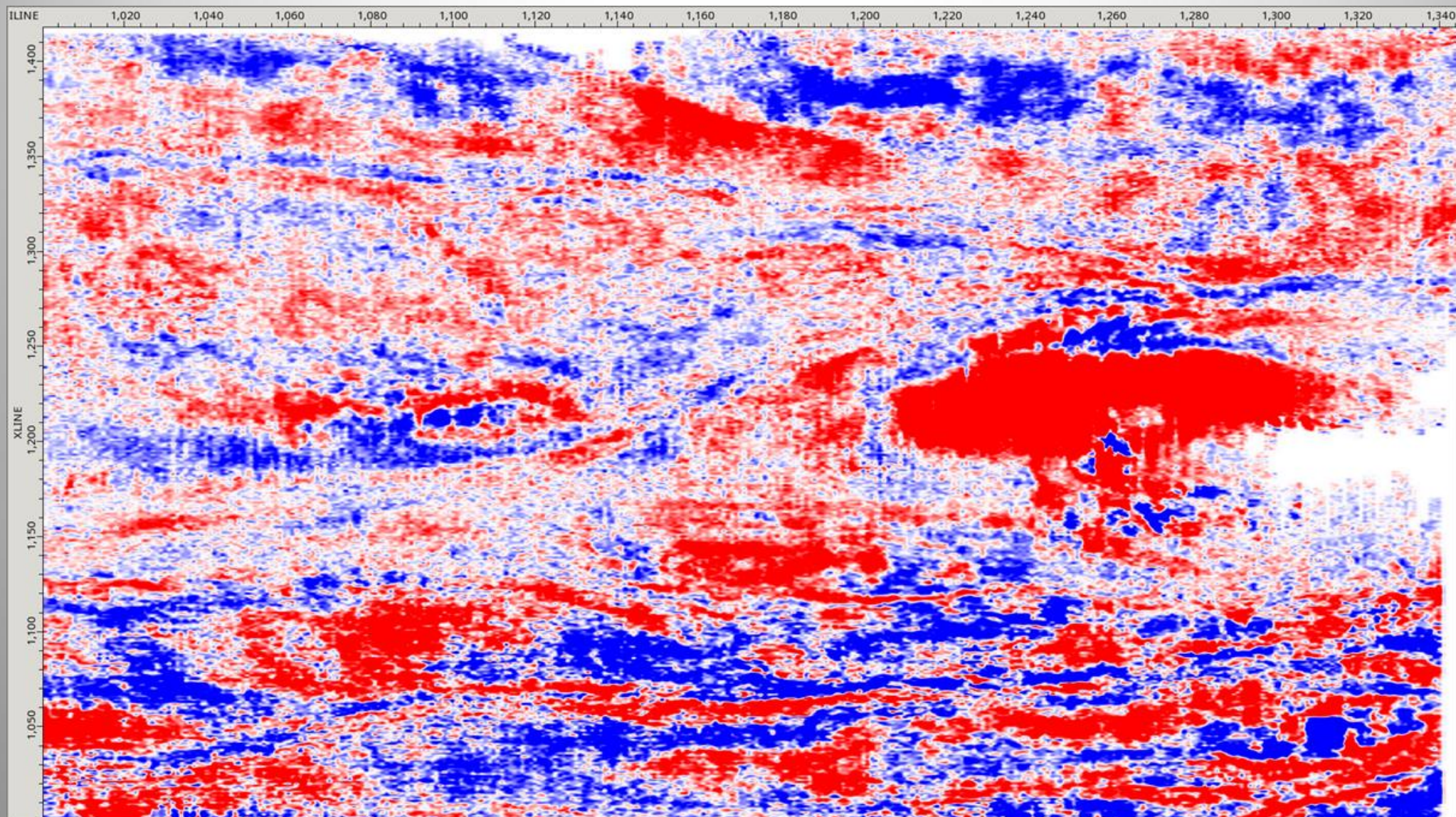
PreSTM using CMP gathers



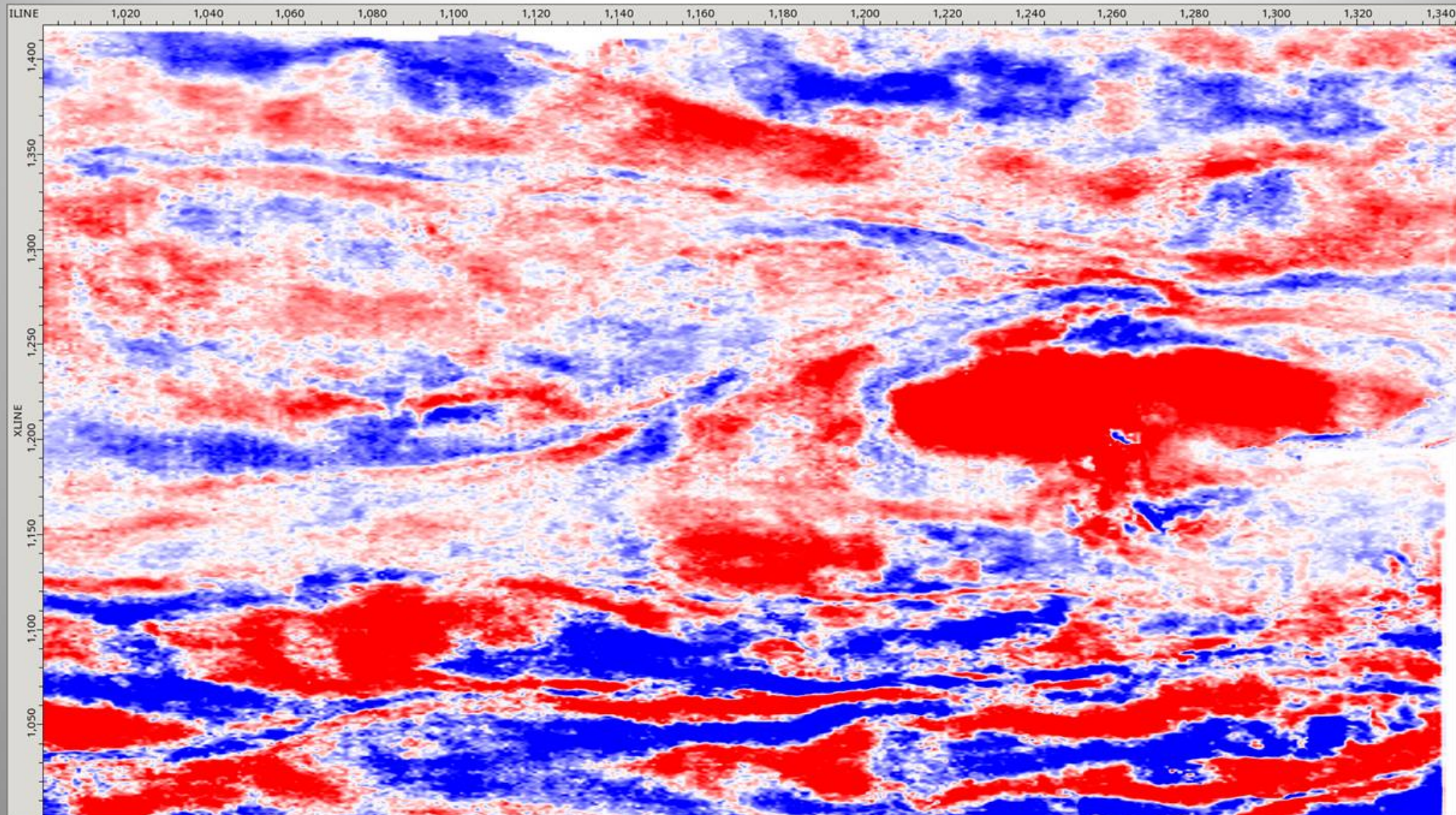
PreSTM using CRS gather



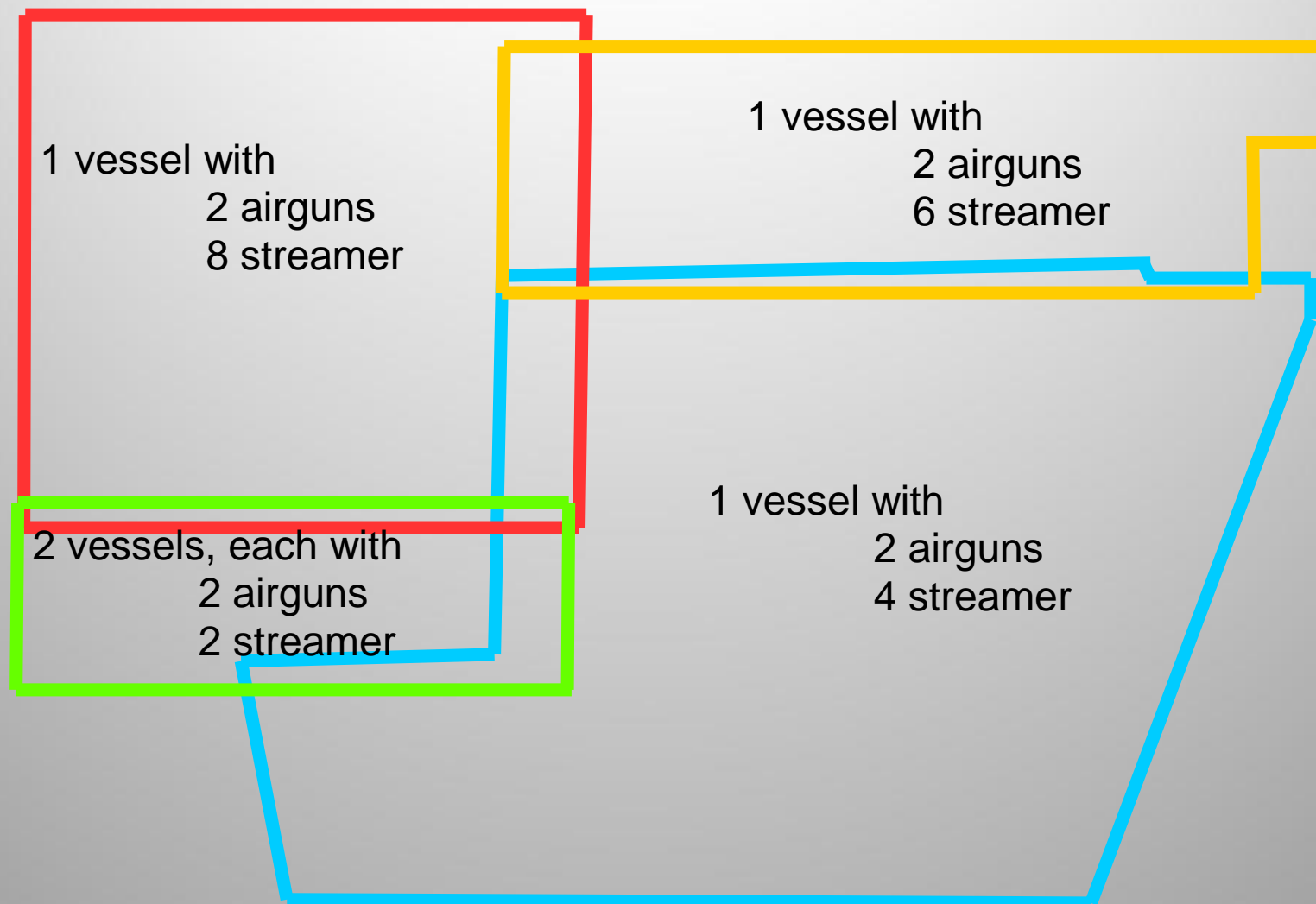
Timeslice 1032 ms of PreSTM



TZ 1032 ms of CRS PreSTM

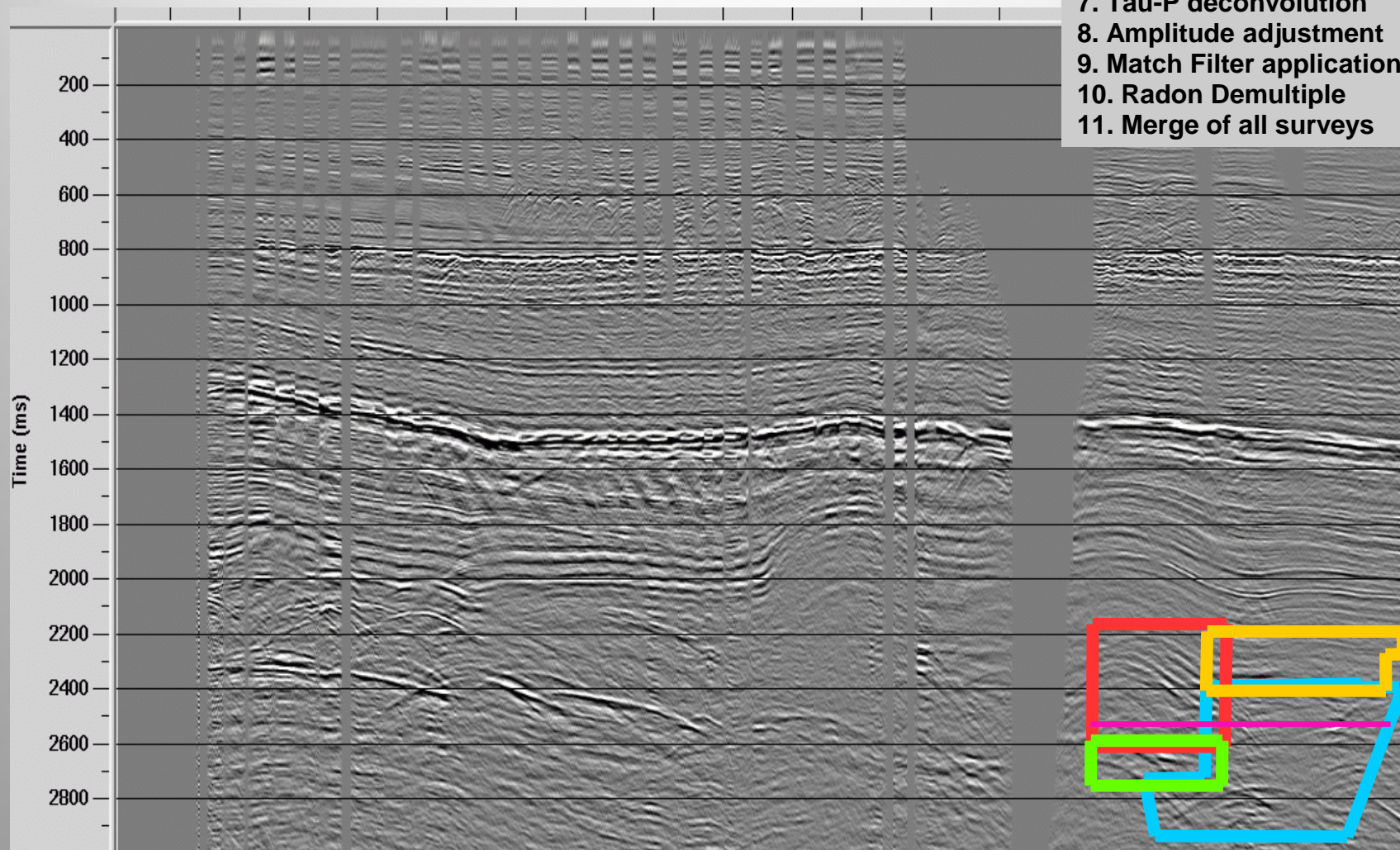


North Sea merge of 4 different acquisition geometries



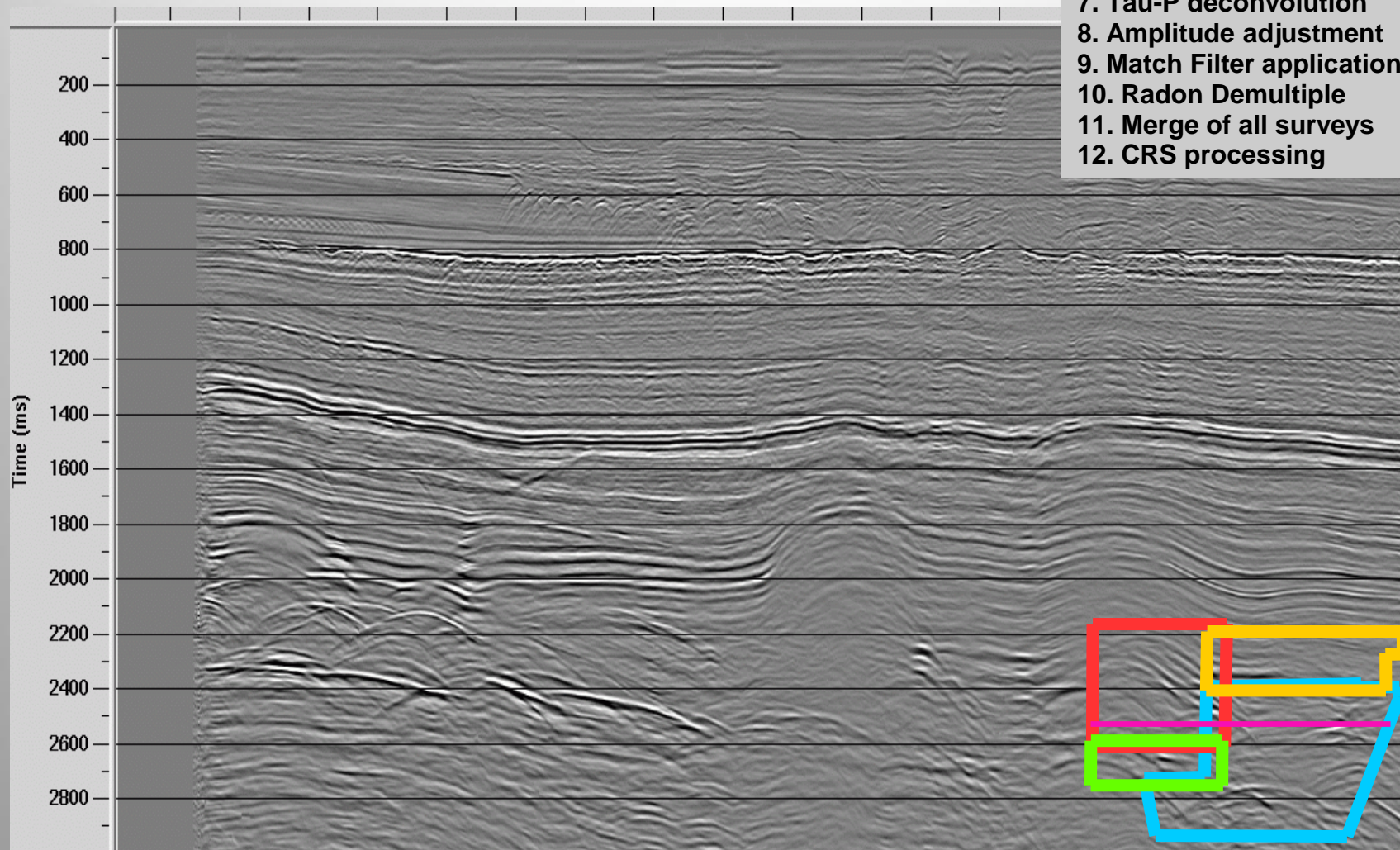
Inline of CMP stack

1. source/receiver static applied
2. True amplitude recovery
3. Low cut filter
4. Source signature deconvolution
5. Debubble
6. Linear denoise
7. Tau-P deconvolution
8. Amplitude adjustment
9. Match Filter application
10. Radon Demultiple
11. Merge of all surveys



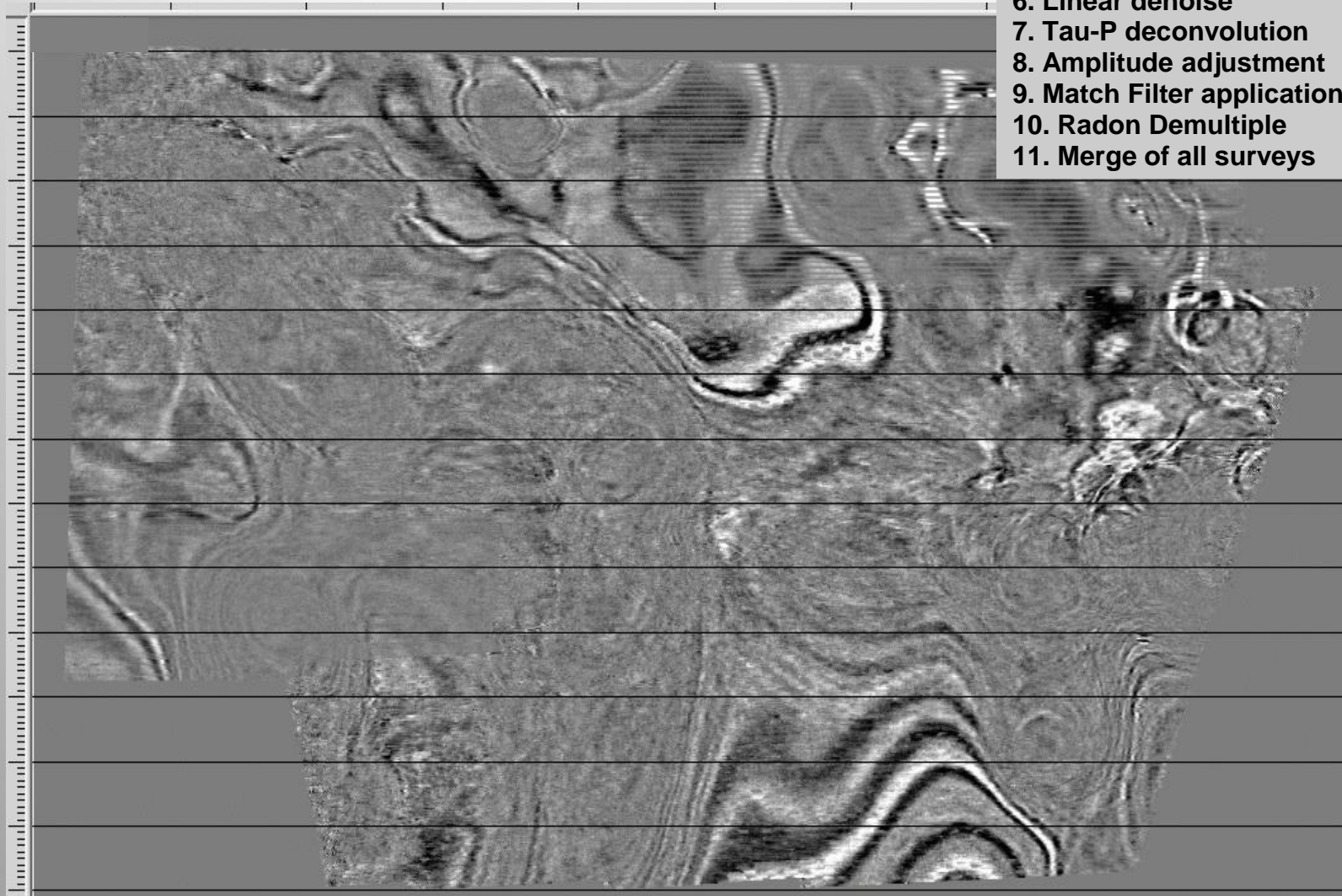
Inline of CRS stack

1. source/receiver static applied
2. True amplitude recovery
3. Low cut filter
4. Source signature deconvolution
5. Debubble
6. Linear denoise
7. Tau-P deconvolution
8. Amplitude adjustment
9. Match Filter application
10. Radon Demultiple
11. Merge of all surveys
12. CRS processing



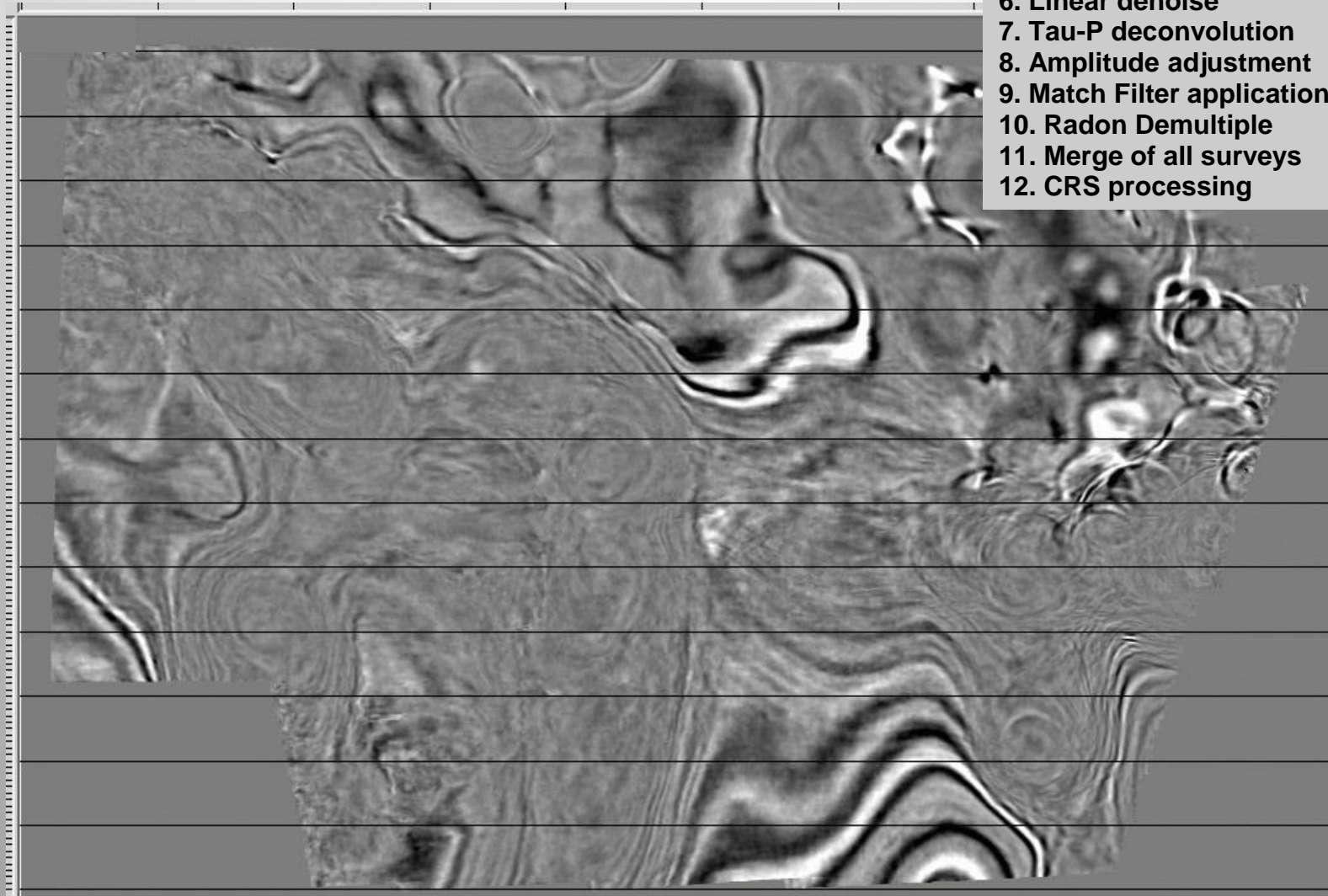
Time slice at 2100 ms of CMP stack

1. source/receiver static applied
2. True amplitude recovery
3. Low cut filter
4. Source signature deconvolution
5. Debubble
6. Linear denoise
7. Tau-P deconvolution
8. Amplitude adjustment
9. Match Filter application
10. Radon Demultiple
11. Merge of all surveys

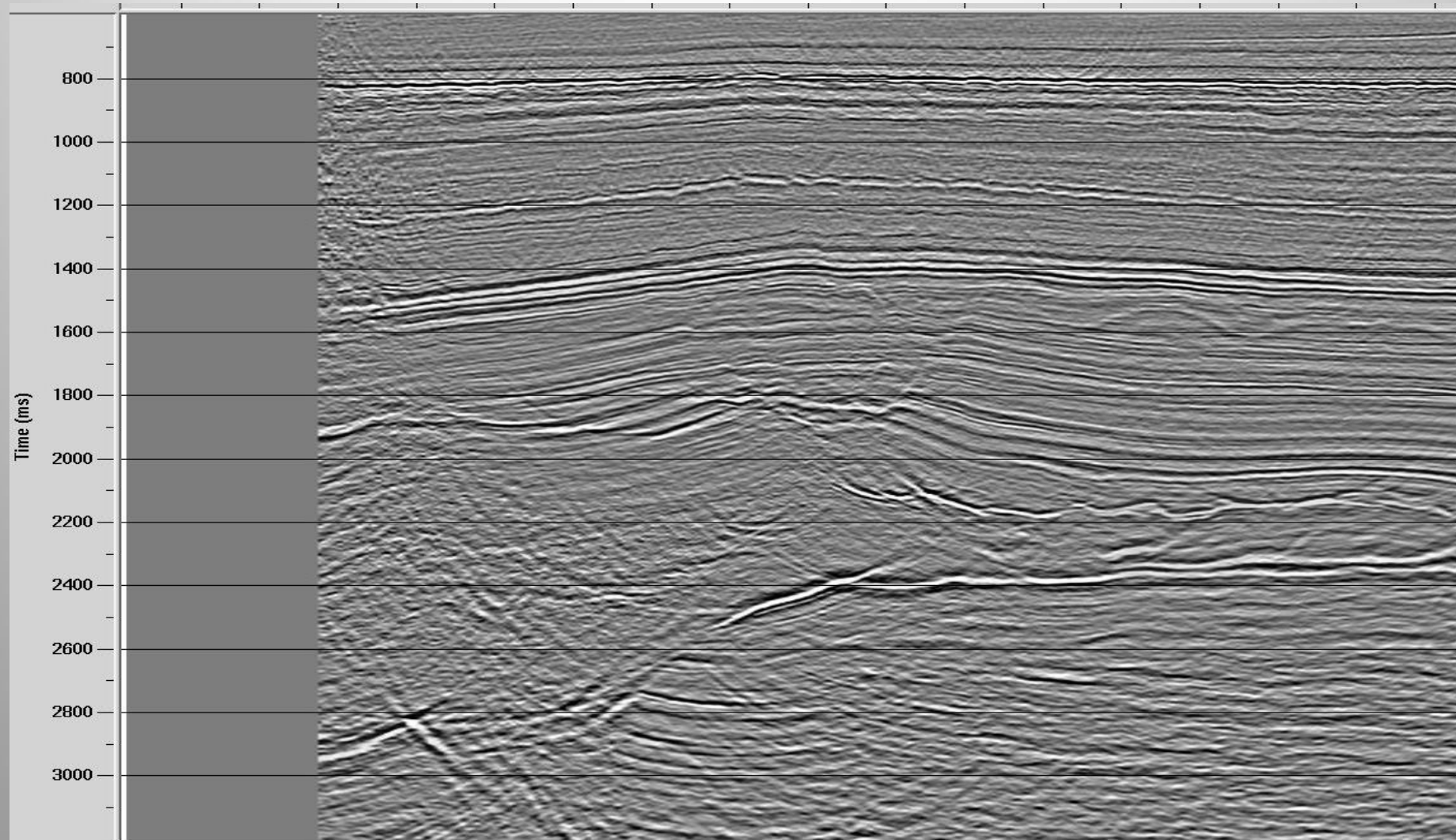


Time slice at 2100 ms of CRS stack

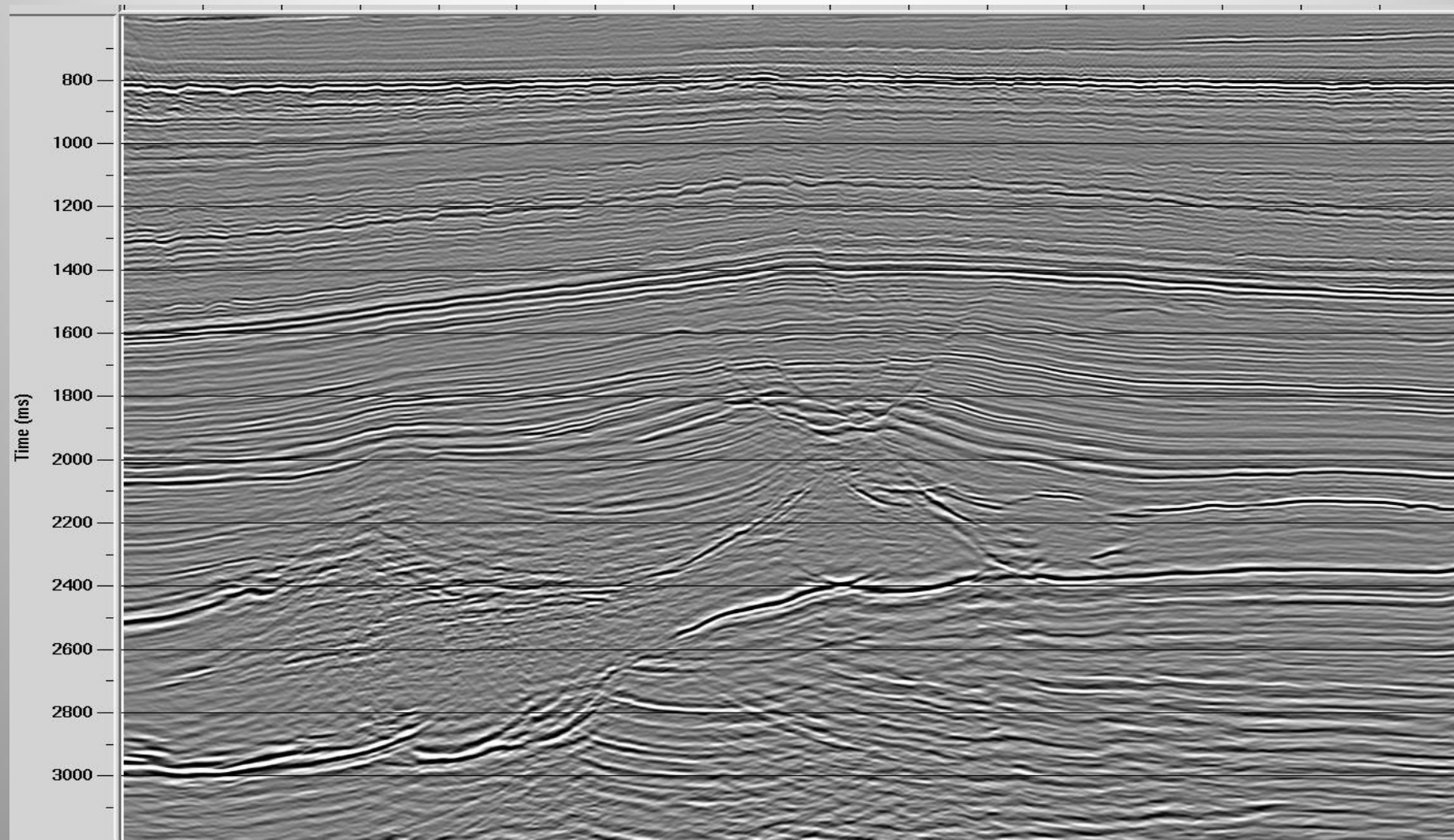
1. source/receiver static applied
2. True amplitude recovery
3. Low cut filter
4. Source signature deconvolution
5. Debubble
6. Linear denoise
7. Tau-P deconvolution
8. Amplitude adjustment
9. Match Filter application
10. Radon Demultiple
11. Merge of all surveys
12. CRS processing



Inline of vintage PreSTM result



Inline of CRS PreSTM



Please contact us for further questions or any comments at

info@teec.de

